

Monitoring tree-level insect population dynamics with multi-scale and multi-source remote sensing

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1 **Abstract**

2 Long term monitoring of the rate-of-change of mountain pine beetle
3 (*Dendroctonus ponderosae* Hopkins) populations requires detailed tree-level
4 information over large areas. This information is used to assess the status of an
5 infestation (e.g., increasing, stable, or decreasing), and to select and evaluate
6 mitigation approaches. In this research project, we develop and demonstrate a
7 prototype monitoring system, which enables the extrapolation of tree level
8 estimates of beetle damage from field data to a larger study area using a double
9 sampling approach, and multi-scale, multi-source, high spatial resolution
10 remotely sensed data.

11

12 Key words: high spatial resolution, QuickBird, digital aerial photography, insect,
13 monitoring, mountain pine beetle

14 **Introduction**

15 Over large areas, information on the location, extent, and severity of mountain
16 pine beetle (*Dendroctonus ponderosae* Hopkins) damage is required to
17 determine the resources needed to address the infestation and subsequently,
18 allocate those resources effectively. Landscape-level (*i.e.*, a management unit
19 approximately 1 million ha in size) information is used to direct the location and
20 intensity of more detailed surveys, which are designed to satisfy operational
21 information needs and allow successful mitigation through accurate detection,

1 location, and enumeration of individual infested trees. Similarly, tree-level (*i.e.*,
2 individual trees or small groups of trees) information is critical for a range of
3 activities, including sanitation logging, the implementation of silvicultural regimes
4 designed to reduce the susceptibility of host trees, as well as direct control
5 treatments. Tree level data of mountain pine beetle damage can be difficult and
6 expensive to acquire; however, statistical sampling approaches may be used
7 whereby samples of detailed data are used to calibrate damage estimates
8 generated from less expensive, and less detailed (but spatially extensive) data.

9 For mountain pine beetle monitoring in a country such as Canada, with
10 vast tracts of forested land (and potential host species), it is necessary to have
11 detailed tree-level information over very large areas (*i.e.*, greater than several
12 million hectares). Unfortunately, data sources suitable for characterizing
13 mountain pine beetle infestations over large areas do not provide sufficient
14 spatial resolution to generate tree-level information—these data sources can
15 provide a reliable estimate of the total area impacted, but cannot provide specific
16 details regarding the number or precise location of individual infested trees.
17 However, by collecting a sub-sample of detailed data that does provide tree-level
18 information, statistical methods can extrapolate estimates of the number of
19 infested trees at the landscape-level. These estimates will not provide information
20 on precise locations of the trees, but can give estimates on the rate of change in
21 the mountain pine beetle population. For example, field measures may be
22 combined with high resolution remotely sensed data (*e.g.*, aerial photography,
23 QuickBird, IKONOS) using double sampling with regression (Wear et al. 1966).

1 This method of double sampling assumes that field measurements of damage or
2 mortality relate to damage information interpreted from the remotely sensed data.
3 A regression-based approach is used to link the field data to the satellite data,
4 thereby providing a means by which damage or mortality estimates can be
5 extrapolated to the landscape-level.

6 ***Goal and objectives***

7 The research presented in this paper is a component of a larger, ongoing
8 project initiated to develop and prototype a monitoring system to provide tree-
9 level estimates of mountain pine beetle caused mortality across a large area,
10 thereby allowing forest managers to determine appropriate management
11 strategies that minimize forest losses and reduce the risk of future infestations
12 (Figure 1). Such a monitoring system provides information essential for
13 determining the status of the infestation, monitoring the long-term impact of the
14 infestation on forest structure, assessing the efficacy of mitigation measures, and
15 reducing the future risk of mountain pine beetle attack. This communication
16 provides details on the methods developed to extrapolate field measurements of
17 tree-level mountain pine beetle red attack damage across a larger area using
18 high spatial resolution remotely sensed data.

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20

<< Please insert Figure 1 about here >>

1 **Background**

2 ***Mountain pine beetle***

3 The current mountain pine beetle outbreak in Western Canada is of historically
4 unprecedented proportions. In 2006, the area affected by the outbreak was
5 estimated to be 9.2 million ha (Westfall 2007) and by 2013, it is projected that the
6 beetle will have killed 80% of the mature pine in British Columbia (Eng et al.
7 2005). The mountain pine beetle's range expansion has been facilitated by large
8 areas of susceptible host species (as a consequence of stand management and
9 fire suppression) and successive years of favourably warm climatic conditions,
10 which enable brood development and survival (Logan and Powell 2001, 2003;
11 Carroll et al. 2004, 2006).

12 When attacked by mountain pine beetle, a tree's foliage will initially remain visibly
13 unchanged; however, signs of attack will be present on the stem (green attack
14 stage). As the tree's foliage fades from green to yellow, the tree is referred to as
15 a fader. Approximately one year following attack, the foliage will turn red (red
16 attack stage), and finally, when the tree loses its foliage, it is considered to be in
17 the grey attack stage (Amman 1982; Henigman et al. 1999, British Columbia
18 Ministry of Forests 1995). Surveying methods and image analysis protocols
19 exploit the visible distinctness of the red attack stage for detection and mapping
20 of infestation location and severity (Wulder et al. 2006a).

1 ***Survey of mountain pine beetle***

2 A variety of survey methods are used to collect information on the location, size,
3 and severity of mountain pine beetle populations, ranging from satellite or aerial
4 platforms, to a tree-by-tree basis on the ground. Thus, the area covered by a
5 survey can vary greatly, as can the level of detail. Each survey method is
6 applicable to different management and a comprehensive description of the
7 survey hierarchy used to detect and map mountain pine beetle in British
8 Columbia is detailed in Wulder et al. (2006b).

9 Field surveys of mountain pine beetle are conducted annually to determine
10 population trends, by estimating the ratio of green attack to red attack trees (G:R)
11 in a forest stand. A ratio greater than one indicates an increasing population,
12 while a ratio less than one indicates a declining population. The G:R ratio is often
13 estimated from a sub-sample of trees along randomly located transects
14 (Safranyik and Carroll 2006). This rate of change information is one of the factors
15 used to determine the management strategy (*i.e.*, suppression, salvage,
16 monitoring) for forest management units in British Columbia (British Columbia
17 Ministry of Forests 1995). The best possible information is used to ensure that
18 the management practices selected are appropriate for the situation; if an
19 incorrect management approach is used, suppression may take longer, or a
20 population that is pre-epidemic may become epidemic and suppression may no
21 longer possible.

1 ***Remote sensing of mountain pine beetle***

2 Remotely sensed data provides unique options for information collection
3 and monitoring to address mountain pine beetle information needs by capturing
4 the location and extent of mountain pine beetle red attack at different scales and
5 with different levels of accuracy and precision (Wulder et al. 2006b), thereby
6 augmenting existing survey methods. The three most important aspects to
7 consider when using remotely sensed data to determine the location and extent
8 of the mountain pine beetle are the spatial, temporal, and spectral characteristics
9 of an attack (Wulder et al. 2006a).

10 **Methods**

11 ***Study area***

12 The project study area encompasses over 6 million ha and is located at the
13 leading edge of an ongoing mountain pine beetle epidemic along the provincial
14 border between British Columbia and Alberta, Canada (Figure 2). Nine sample
15 locations, each with an area of 6400 ha, were selected within the study area and
16 high spatial resolution remotely sensed imagery and field data were acquired
17 within these sample locations (Figure 3). These sample plots were strategically
18 placed in areas of high risk to mountain pine beetle attack based on a
19 susceptibility rating outlined by Shore and Safranyik (1992), and using forest
20 inventory data (*i.e.*, stand age and density, dbh, species composition, location,

1 and elevation). The methods presented herein were developed and tested on
2 Site 9 (Figure 3).

3 << Please insert Figure 2 about here >>

4 << Please insert Figure 3 about here >>

5 Approximately 72% of the study area (south and west) is in the Montane
6 Cordillera ecozone. The remaining 28% of the study area to the north and the
7 east is the Boreal Plains ecozone. Tree species of the forests within the region
8 are predominately lodgepole pine (*Pinus contorta* Dougl ex Loud. Var. *latifolia*
9 Engelm.), with small proportions of alpine fir (*Abies lasiocarpa* Nutt.), Engelmann
10 spruce (*Picea engelmannii* (Parry) Engelm.), white spruce (*Picea glauca*
11 (Monech) Voss), black spruce (*Picea mariana* (Mill) BSP), jack pine (*Pinus*
12 *banksiana* Lamb.), and tamarack (*Larix laricina* (Dr Roi) K. Kock).

13 Located in the Dawson Creek Timber Supply Area (TSA) of British
14 Columbia and the Northwest Boreal Forest Management Unit in Alberta, the
15 study area also includes provincial and federal parklands. These areas represent
16 high-value, high-profile stands, which may be subject to aggressive direct control
17 measures such as yearly sanitation harvesting and single tree treatments, such
18 as those that have become commonplace in other regions impacted by mountain
19 pine beetle. The study area has no recorded history of mountain pine beetle
20 infestation, while areas to the northwest and southwest of the study area are
21 currently at endemic infestation levels. Due to the abundance of large-diameter
22 lodgepole pine in the study area, an increasing trend in the beetle population is
23 anticipated.

1 **Data**

2 **Field data**

3 Field data was collected by ground crews from August 9th to 29th, 2006 and again
4 from July 27th to August 12th, 2007. Measurements of individual trees included:
5 stem diameter, crown dimensions, tree height, trees species, and mountain pine
6 beetle health status. Stand-based measurements included, slope, aspect, and
7 the geographic location of plot centre. In 2006, 26 field plots were visited across
8 all nine sample sites, however only one plot was found to have red attack
9 damage. In 2007, 27 field plots were visited, again across all sites, with 164 red
10 attack trees identified. In Site 9, four field plots were sampled in 2006 and no red
11 attack was identified; in 2007, nine field plots were sampled and 61 red attack
12 trees were located (Table 1).

13 << Please insert Table 1 about here >>

14 **Forest inventory**

15 Forest inventory data for the portion of the study area located in British Columbia
16 was obtained from the Ministry of Forests and Range and conforms to the
17 standards for Vegetation Resources Inventory (VRI) in British Columbia (British
18 Columbia Ministry of Sustainable Resource Management, 2002). Forest
19 inventory for the portion of the study area located in Alberta was obtained from
20 Weyerhaeuser for their FMA area, and from the Alberta Sustainable Resource
21 Development agency for the other areas of the forest management unit, including
22 designated wilderness areas and reserves. The Alberta inventories were

1 compiled according to Alberta Vegetation Inventory Standards (Alberta
2 Sustainable Resource Development 2005).

3 **High-spatial resolution remotely sensed data**

4 Annual high spatial resolution satellite images, such as those obtained from
5 QuickBird, provide the mechanism to detect and extrapolate tree level
6 information on mountain pine beetle red attack damage. QuickBird imagery
7 contains four multispectral bands with a 2.5 m spatial resolution: 0.45-0.52 μm
8 (blue); 0.52-0.60 μm (green); 0.63-0.69 μm (red); 0.76-0.90 μm (near infra-red);
9 and a panchromatic band (0.45-0.90 μm), with a 0.68 m spatial resolution (Birk et
10 al. 2003). QuickBird imagery was ordered in 2006 and 2007 for Site 9, however
11 persistent cloud cover prevented successful image acquisition in 2007. The 2006
12 QuickBird image was acquired on July 20, with a sun elevation angle of 54.41
13 degrees and the off-nadir view angle of 11.26 degrees. The QuickBird imagery
14 was orthorectified to Terrain Resource Information Management II (TRIM II)
15 aerial photography (British Columbia Ministry of Sustainable Resource
16 Management, 1997) and a Digital Elevation Model (DEM) from Canadian Digital
17 Elevation Data (CDED) provided by GeoBase at a scale of 1:50,000. All
18 processing used a satellite orbital model (after Toutin 2004) with cubic
19 convolution resampling in PCI Geomatica V9.1.8. The panchromatic and
20 multispectral bands were orthorectified individually and had root-mean-square
21 (RMS) errors of 1.24 pixels (0.74 m) and 0.3 pixels (0.73 m), respectively. To
22 mitigate the lack of a satellite-based source of high spatial resolution imagery, in
23 2007, 40 cm digital aerial photography was acquired over the sample sites in

1 September 2007 using the same camera and acquisition parameters as the 10
2 cm photos.

3 In 2006 and 2007, digital colour aerial imagery was collected prior to the
4 commencement of field surveys. Imagery was acquired with a Canon EOS-1Ds
5 Mark II camera (with a focal length of 85 mm), mounted on a fixed wing aircraft
6 flying at 1100 m (Terrasaurus, Vancouver, British Columbia, Canada). Images
7 were collected over the centre point of each plot, resulting in 10 cm spatial
8 resolution. Imagery was orthorectified to a UTM NAD 83 projection with each
9 photograph covering an area of approximately 0.14 km² (0.44 km x 0.31 km,
10 4850 x 3110 pixels). Imagery was recorded in 3 channels representing the
11 spectral ranges: 0.6 – 0.7 µm (red), 0.5 – 0.6 µm (green), and 0.4 – 0.5 µm
12 (blue).

13 The orthorectified panchromatic QuickBird image was used as the
14 reference image to which all other aerial images were registered. The registration
15 was done using a third order polynomial and cubic convolution re-sampling
16 algorithm. The final RMS error for the 10 cm images was 10.87 pixels (1.09 m)
17 and for the 40 cm aerial image, the RMS error was 3.84 pixels (1.54 m).

18 *Image analysis*

19 The analysis procedures implemented are outlined in Figure 4 and described in
20 the following sections.

21 << Please insert Figure 4 about here >>

1 **Image masks**

2 Forest inventory data were used to generate the pine mask of forest stands that
3 contained greater than or equal to 50% pine. These masks were then applied to
4 the 2006 QuickBird imagery to constrain subsequent analyses to those stands
5 that contain pine, thereby reducing the total area analyzed, as well as reducing
6 the spectral variability of the area subject to analysis (Rogan and Miller 2006). An
7 additional mask was generated to remove cloud and cloud shadow areas within
8 the sample site.

9 **Image segmentation**

10 Since the aerial and satellite imagery were acquired on different dates, there are
11 differences in viewing geometry and illumination conditions. These factors,
12 combined with the potential for error in co-registration of multiple scales and
13 dates (Weber et al. In press), made tracking the health status of individual trees
14 through the different data sources and years a challenge. To mitigate this
15 potential source of error, segmentation of the 2006 QuickBird multispectral
16 imagery was used to provide a context for tracking tree sub-populations through
17 time (Wulder et al. In press). Segments were generated using all four QuickBird
18 multispectral bands in eCognition software (Definiens GmbH, Munchen,
19 Germany) in two passes with equal weights for all bands. The first pass used the
20 following parameters: scale = 15; shape = 0.5; colour = 0.5; compactness = 0.75;
21 smoothness = 0.25, while the second pass used: scale = 15; shape = 0.9; colour
22 = 0.1; compactness = 1.0; smoothness = 0.

1 **Stem counts**

2 First, individual tree crowns were manually delineated on the 10 cm air photos.
3 This provided a useful information source for validating stem counts generated
4 from the QuickBird data, and for enumerating the number of red attack trees
5 identified on the 10 cm photos. In order to generate stem counts for the entire
6 sample site, a local maxima (LM) filter (Wulder et al. 2000) was applied to the
7 2006 panchromatic QuickBird image. When a LM filter is applied to high spatial
8 resolution imagery, individual trees can be identified as local regions of relatively
9 higher reflectance (in appropriate spectral channels, such as near infrared or
10 panchromatic) (Dralle and Rudemo 1997). The LM filter passes over all pixels in
11 an image, and identifies those that have an equal or higher reflectance within a
12 threshold range than the surrounding pixels. This requires that the image
13 resolution is finer than the crown size of the trees, so that each tree crown is
14 represented by multiple pixels. The LM filter has a bias towards large tree
15 crowns, and a higher error of omission towards smaller tree crowns; however, the
16 impact of this bias is minimal for this project, because trees with smaller crowns
17 are generally younger and not typically as susceptible to mountain pine beetle
18 attack (Shore et al. 2000).

19 For this study, a 3- by 3-pixel LM filter was applied to identify individual
20 tree crowns. The identified LM pixels were then converted to a vector point data
21 set representing individual stems. The LM stems and the image segments
22 generated from the 2006 QuickBird imagery were used for the 2007 analysis, as
23 it was assumed that the number of stems and segments would be consistent

1 over the two years. The LM tree counts were validated against manual tree
2 counts from the 10 cm imagery. A calibration factor was derived from the
3 relationship between the 10 cm and QuickBird stem counts, and this factor was
4 then applied to the QuickBird stem counts to generate a final, calibrated stem
5 count estimate for the entire sample site.

6 **Red attack detection on 10 cm aerial imagery**

7 Red attack trees that were identified in the 2007 field surveys were identified and
8 manually delineated on the 10 cm aerial photography. To identify red attack trees
9 outside of the field plot areas on the 10 cm aerial imagery, a red-green index
10 (RGI) was calculated by dividing the red image channel by the green image
11 channel using a similar approach developed by Coops et al. (2006) to identify red
12 attack damage from QuickBird imagery. Once the RGI was calculated for each of
13 the 2007 10cm images, a RGI threshold range was generated using the known
14 red attack trees from the field plots. Pixels with a RGI within this range were
15 identified as red attack in a bitmap layer. To reduce false positive red attack
16 identification, the bitmap layer was converted into vector polygons, and those
17 polygons with an area less than 1.44 m^2 (corresponding to an area 1.2m by
18 1.2m, or four QuickBird panchromatic pixels) were eliminated. This cut-off
19 corresponds roughly to the crown area that is identifiable using the LM filter
20 approach. The remaining areas identified as red attack were each visually
21 assessed, and those that were deemed not to be red attack trees were
22 eliminated. Individual red attack trees were enumerated. The result of this
23 process was a calibration and validation layer of red attack trees on the 10 cm

1 imagery that can be used to calibrate and verify red attack detection from coarser
2 image sources.

3 **Red attack detection on 2006 QuickBird and 40 cm air photos**

4 The RGI approach used for red attack detection on the 10 cm imagery was also
5 applied to the 2006 QuickBird multispectral data, and to the 40 cm photos
6 collected in 2007, which provide the surrogate for the 2007 high spatial satellite
7 resolution imagery. The RGI was calculated for the 2007 40 cm aerial imagery
8 under the pine mask and a threshold range was developed using those areas
9 identified as red attack on the 10 cm imagery. As with the 10 cm imagery, the
10 resulting bitmap layer was converted into vector format and those polygons with
11 an area less than 1.44 m² were eliminated.

12 The point layer representing the individual tree stems was then overlaid
13 with the red attack areas and those stems found within a corresponding red
14 attack area were labelled as red attack. Trees that are red attack in 2007 are
15 assumed to have been green-attack in 2006, facilitating an estimate of the G:R
16 ratio for 2006.

17 **Calibration and validation**

18 Both stem counts and red attack detection estimates generated with the 40 cm
19 photos were calibrated and validated using corresponding estimates from the 10
20 cm photos (Figure 5).

1 Stem counts

2 In order to assess stem counts generated from the LM filter, manual stem counts
3 were conducted on the 10 cm digital imagery within 40 randomly selected
4 segments. The relationship between the LM-derived stem counts and the manual
5 stem counts was assessed using a simple linear regression and an adjustment
6 factor was calculated. T-tests were used to assess if the stem counts generated
7 from the QuickBird and the 10 cm photos were significantly different prior to and
8 following the application of the adjustment factor.

9 Red attack

10 Estimates of red attack generated from the field data and from the 10 cm photos
11 were used to iteratively modify the threshold range of RGI values used to identify
12 red attack pixels from the 40 cm photos. To calibrate the threshold range, the
13 results of the thresholding were visually compared to the 10cm images to assess
14 the effectiveness in terms of success at correctly identifying red attack while
15 minimizing false positive identification. The threshold range was iteratively
16 adjusted to improve the red attack estimates, and the results were assessed
17 again until an optimum threshold range was identified. After the optimum
18 threshold range was selected, the red attack area was identified and the LM-
19 derived stems were overlaid with the red attack layer to assign attack status to
20 the stems. Red attack estimates from the 10 cm photos were also used in a
21 double sampling with regression approach to calibrate broad estimates of red
22 attack damage for Site 9 made from the 40 cm photos.

23 << Please insert Figure 5 about here >>

1 ***Double sampling***

2 Double sampling with stratification is an established method for integrating
3 remotely sensed data with ground samples (USDA Forest Service, 1992).
4 Selected classes (such as red attack trees) are randomly re-sampled at a higher
5 level of detail to provide more information about that class (Frayser and Furnival
6 1999). A regression between the high accuracy ground data and lower accuracy
7 remotely sensed data is used to adjust the estimates over the entire area
8 (Bickford 1952). The advantage of double sampling is that expensive data
9 collection methods, such as field sampling are minimized, while the estimates
10 from lower cost, broader area data sources, such as satellite imagery, are
11 optimized. In this project, the double sampling strategy is applied in using the
12 field data to correct the high resolution aerial estimates of red attack trees, which
13 in turn are used to correct the estimates of red attack trees from the high-
14 resolution satellite imagery.

15 In this study, double sampling was used to extrapolate tree-level estimates
16 of red attack damage across a larger study area. The high resolution 10cm
17 imagery was used to calibrate the LM-derived stem counts to provide a more
18 accurate segment based tree count covering the entire study site. The resulting
19 calibration factor was applied to the entire study site to provide an adjusted red
20 attack count extrapolated over the entire area of Site 9.

1 **Results and Discussion**

2 ***Image segmentation***

3 The number of segments generated for Site 9 was 41,119; however, only those
4 segments that had their centroid within the pine mask area were used for further
5 analysis, resulting in 19,297 segments. For the 2007 calibration and validation
6 data, 510 segments that had corresponding coverage with the 10 cm
7 photography were used for both stem counts and red attack detection (Table 2).

8 << Please insert about here >>

9 ***Validation of stem counts***

10 To validate the LM-derived stem counts, 40 segments were selected at random
11 and the stem counts were compared to the manual stem counts. Table 3
12 contains a summary of stem count results. Although the stem counts were very
13 similar (Figure 6, $R^2=0.94$), there was a significant difference between the
14 manual segment stem count generated from the 10 cm photos and the segment
15 stem count generated from the LM filter applied to the QuickBird panchromatic
16 image ($\alpha = 0.95$, $p= 0.006$).

17 << Please insert Table 3 about here >>

18 To account for the difference in stem counts, a simple linear regression
19 was used to generate an adjustment factor to calibrate the LM-derived stem
20 counts to the manual stem counts (Figure 6). The adjustment factor for the LM
21 tree counts was:

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$$LM_{adj} = 1.209018 * LM_{QB}$$

After application of this adjustment to the stem counts in each segment, no significant difference between the two stem count estimates was found ($\alpha = 0.95$, $p = 0.85$).

<< Please insert Figure 6 about here >>

Calibration and validation of red attack detection

To obtain red attack counts for the 510 segment subset used as calibration and validation data, the trees identified as red attack in the 2007 field visits were used to derive a threshold range for the RGI values generated from 10 cm photos. The threshold range was identified as digital numbers (DNs) from 1.1 to 1.9 and pixels identified in this range were then manually assessed for red attack status (Table 4). Only ten segments had five or more red attack trees, and the maximum number of trees per segment was 14. The results of the 2007 RGI red attack mapping using the 10 cm photos were manually compared to the red attack trees identified in the 2007 field plots, and of the 220 trees that had a health status recorded in the field, only one tree on the 10 cm photo was incorrectly identified as red attack, while four red attack trees identified in the field were omitted on the 10 cm image mapping. The four omitted trees had small crowns, or were immediately adjacent to other red attack trees. The RGI was calculated for the 2006 10 cm imagery; however, in 2006 the field surveys had found no evidence of red attack, and based on the results of the RGI and a

1 manual assessments of the 10 cm imagery, there was no red attack evident in
2 that year.

3 The RGI approach described above was applied to the 40 cm photos
4 acquired in 2007. The threshold was determined iteratively based on red attack
5 identified on the 10 cm imagery as DN_s from 1.0 to 1.9. The 40 cm imagery was
6 taken late in the year, and some of the hardwoods had already started to change
7 colour. This was a source of commission error. In future, care must be taken to
8 acquire the imagery early enough to avoid this problem again. Applying the
9 threshold range resulted in a total red attack area for the 510 segments of 1650
10 m². When the LM-derived stems were overlaid on the red attack areas, a total of
11 139 trees were identified as red attack, to which the LM adjustment factor was
12 applied. The same approach was then applied to the remaining 18,797 segments
13 (Table 4).

14 << Please insert Table 4 about here >>

15 ***Double sampling***

16 Double sampling with regression was used to combine the estimates of red
17 attack damage from the 40 cm photos with the red attack estimates from the field
18 data and the 10 cm photos (Ciesla 2000). The objective is to refine the estimates
19 generated from the 40 cm photos and to quantify estimation error for the sample
20 site. Double sampling with regression uses two stages; the first stage requires a
21 large sample collected via remote sensing (*i.e.*, 40 cm photos), while the second
22 stage requires a sub-sample of the first stage where more detailed data is

1 collected (*i.e.*, 10 cm photos). Of the 75 segments that had red attack identified
2 from the 10 cm photos, 22 had red attack identified on the 40 cm photos. These
3 22 segments were used for the double sampling approach. A linear regression is
4 used to determine the relationship between the estimates of red attack acquired
5 from the 10 cm and 40 cm photos. The final estimate of red attack for the larger
6 area is achieved by using the regression to adjust the estimates from the first
7 stage (Ciesla 2000).

8 Following Wear et al. (1966) and Ciesla (2000), the first step was to
9 generate the mean red attack count for the large sample (40 cm; $n=2399$
10 segments), which was 2.2 (Table 4). The second step was then to generate the
11 mean red attack count for the 10 cm and 40 cm photos for the small sample
12 ($n=22$), which were 3.8 and 3.18 respectively, and determine the linear
13 regression of 10 cm red attack counts over 40 cm red attack counts for the small
14 sample (Figure 7):

$$15 \quad y = 1.22 + 0.815x$$

16 This regression was found to be significant at the 99-percent level ($F=16.34$
17 which is > 8.1 at 1 and 20 degrees of freedom), with an $R^2=0.45$ ($p < 0.001$,
18 standard error=2.5 red attack trees). This regression was used to generate a
19 revised estimate of the number of red attack trees within Site 9 as follows (Ciesla,
20 2000):

$$21 \quad RA_{40cm(adj)} = RA_{10cm} + b(RA_{40cm(LS)} - RA_{40cm(SS)})$$

1 where RA_{10cm} is the mean red attack count from the 10 cm photos (3.8; $n=22$);
2 $RA_{40cm(LS)}$ is the mean red attack count from the 40 cm photos for the large
3 sample (LS) (2.2; $n=2399$); and, $RA_{40cm(SS)}$ is the mean red attack count for the
4 photos from the small sample (SS) (3.18; $n=22$):

$$\begin{aligned} RA_{40cm(adj)} &= 3.8 + 0.815(2.2 - 3.18) \\ &= 3.01 \text{ red attack trees/segment} \end{aligned}$$

8 Applying this relationship, the total number of red attack trees in Site 9 for 2007 is
9 estimated to be 7240. Using the method outlined by Ciesla (2000), the sampling
10 error rate for the developed model was estimated to be 0.055% or ± 397 trees.

11 << Please insert Figure 7 about here >>

12 The results of this study suggest that some level of stratification by attack
13 level can be effective in improving the success of the double sampling approach.
14 Low levels of red attack, as seen in this study site may be more difficult to
15 calibrate compared to high levels of red attack. With higher levels of attack, the
16 RGI threshold range used to identify red attack areas can also be optimized to
17 reduce the error of commission, since small groups of trees will be more easily
18 identified than single trees. At low levels of attack, where the dominant scenario
19 is a single red attack tree per segment, a single incorrectly identified red attack
20 tree can have a significant impact on the error, making it difficult to build a single
21 model that captures the variability in attack conditions throughout the study site.

1 ***Estimating the G:R for 2006***

2 Counts of individual trees attacked in successive years provide an indication of
3 beetle population growth and dynamics. To facilitate an estimate of G:R, the
4 amount of red attack observed in 2007 is back-cast as green attack in 2006. In
5 2007, the total amount of red attack estimated over the sample site was 7240
6 trees, distributed over 2399 segments. If these trees were green attack in 2006,
7 the G:R for Site 9 is estimated at 3.01:0. As would be expected in an area that is
8 on the leading edge of an epidemic, the rate of increase is high, due to an influx
9 of beetles from external populations as opposed to an in situ population
10 explosion. A G:R ratio was calculated for the 510 segment subset using the 10
11 cm photos resulting in a ratio of 3.16:0. This G:R closely corresponds to the ratio
12 generated using the adjusted totals of red attack for the larger area from the
13 double sampling approach.

14 In the Peace Forest District (Figure 2), where the majority of the project's
15 larger study area is located, the average G:R was 12:1, with a maximum of 163:1
16 and a minimum of 1.1:1 (Westfall 2007). Generally, the absolute maximum
17 possible G:R is believed to be 10:1 (British Columbia Ministry of Forests 1995),
18 with the acceptable biological limit being 5:1 (Westfall 2007). It should be
19 reiterated that these G:R are based on the assumption of in situ population
20 growth rather than immigration and must therefore be interpreted with caution.
21 Our estimated G:R is reflective of the unique conditions in this area (Carroll
22 2007).

1 **Conclusions**

2 In British Columbia, the spatial extent of the current infestation is such that
3 information needs are now focused on monitoring the areas on the leading edge
4 of the infestation, and efforts are directed towards minimizing mountain pine
5 beetle population growth and avert spread into the boreal forest (Carroll et al.
6 2006; Logan and Powell 2001). A sample-based large area monitoring for forest
7 health status is desired to track the infestation population status and dynamics,
8 as well as the impacts of mitigation upon these populations. Monitoring of tree-
9 level health status is required to provide sufficiently detailed information for
10 tracking infestation population status and dynamics. Using a range of
11 approaches, we have integrated spatial and spectral information from differing
12 data types to prototype a tree-level monitoring program. Individual trees may be
13 identified, insect attack status can be produced (from different image sources),
14 and combined over time to produce information on mountain pine beetle
15 population and change. Based upon the findings of this monitoring system
16 prototype, we have demonstrated that tree level monitoring of health status is
17 possible, including when using differing image types in a multi-year monitoring
18 program is possible.

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7 collection.

8

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1 **Tables**

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3
4

Table 1. Summary of trees identified in the field plots (2007) and on the 10 cm imagery.

Health Status	Total # of trees
Dead	10
Healthy	146
Green attack	3
Red attack	61
Total	220

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Table 2. Summary of segmentation results.

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	Number of segments	Minimum segment size (m²)	Maximum segment size (m²)	Average segment size (m²)
Site 9	41,119	52	16,214	1,547
Masked image area	19,297	52	12,200	1,677
Calibration/validation	510	121	7,010	1,606

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Table 3. Summary of LM filter tree count results.

	Number of segments	Minimum tree count	Maximum tree count	Average tree count/segment
Masked image area	19,297	0	1,373	142
Calibration/validation	510	0	876	146
LM calibration set	40	5	998	175

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Table 4. Summary of red attack counts.

Data	Number of segments	RA count by area	RA count Final	Segments with RA	Average RA per segment
10cm	510	-	237	75	3.16
40cm	510	139	168	54	3.11
40cm	18,797	4376	5291	2399	2.2

1 **Figures**

2 Figure 1. Theoretical design of multi-scale, tree-level, mountain pine beetle monitoring program.

3

4 Figure 2. Study area on border of British Columbia and Alberta, Canada.

5

6 Figure 3. Area of interest, showing sample site locations, and pine / elevation mask over Landsat
7 image (path 47, row 22) backdrop.

8

9 Figure 4. Processing workflow.

10

11 Figure 5. Available imagery showing the impact of resolution differences. The same individual red
12 attack tree crowns are circled in red, and healthy trees are circled in green.

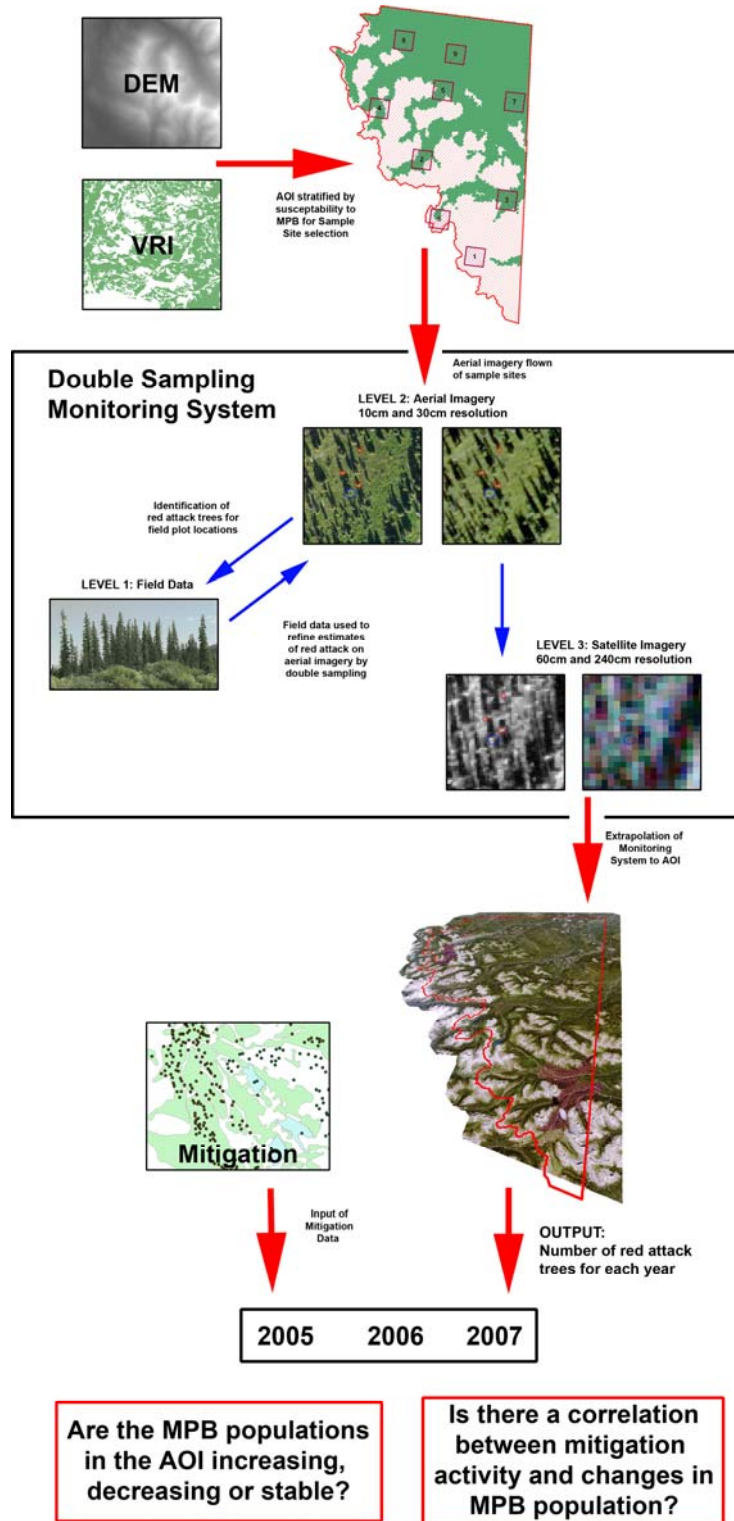
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14 Figure 6. Stem counts/ha estimated via manual interpretation of 10 cm imagery related to stem
15 counts from LM filter of QuickBird panchromatic imagery ($n=40$).

16

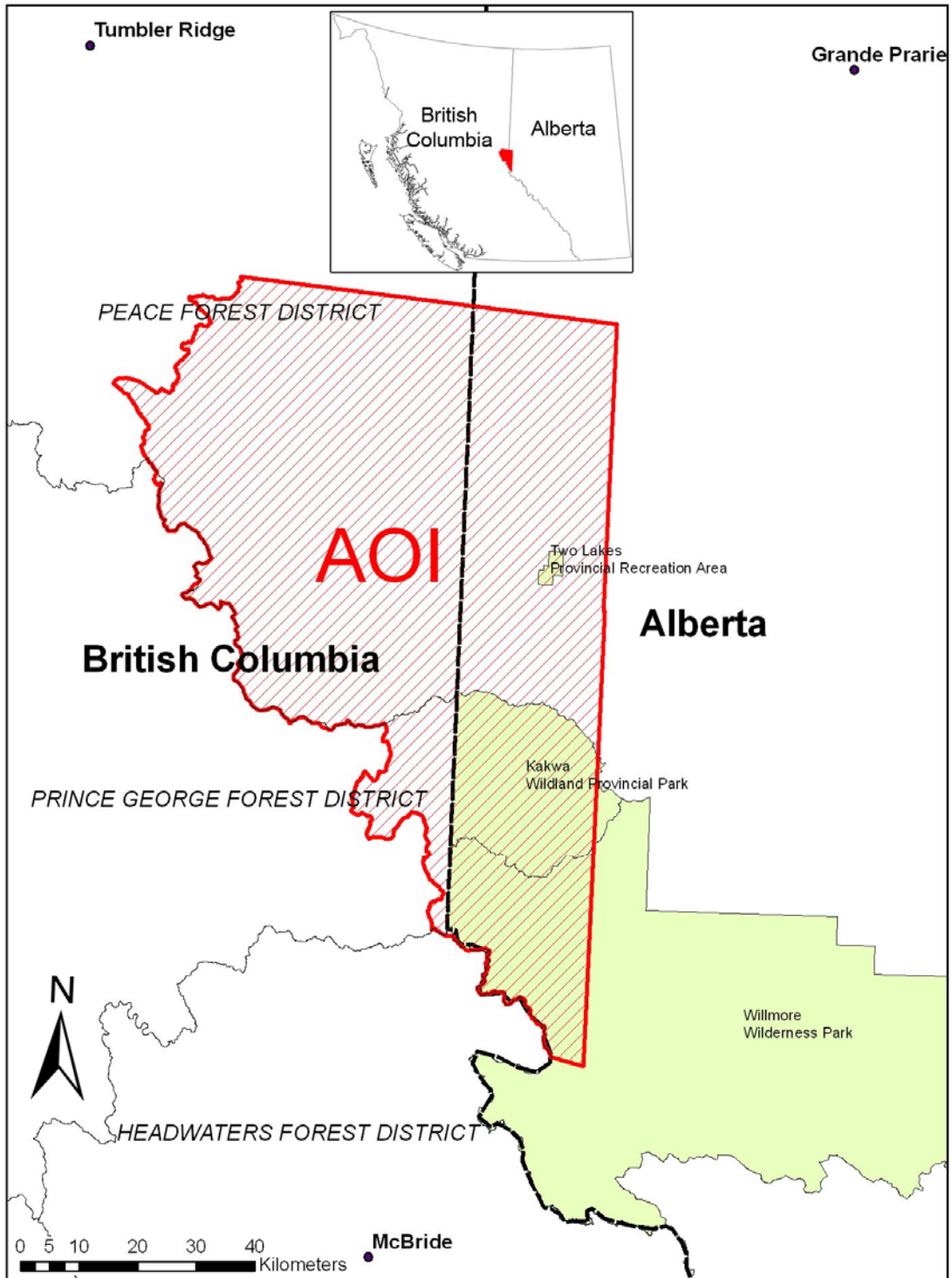
17 Figure 7. Number of trees identified as red attack through manual interpretation of 10cm imagery
18 related to red attack predictions from 40cm imagery, with LM adjustment factor applied
19 ($n=22$).

1 **Figure 1**



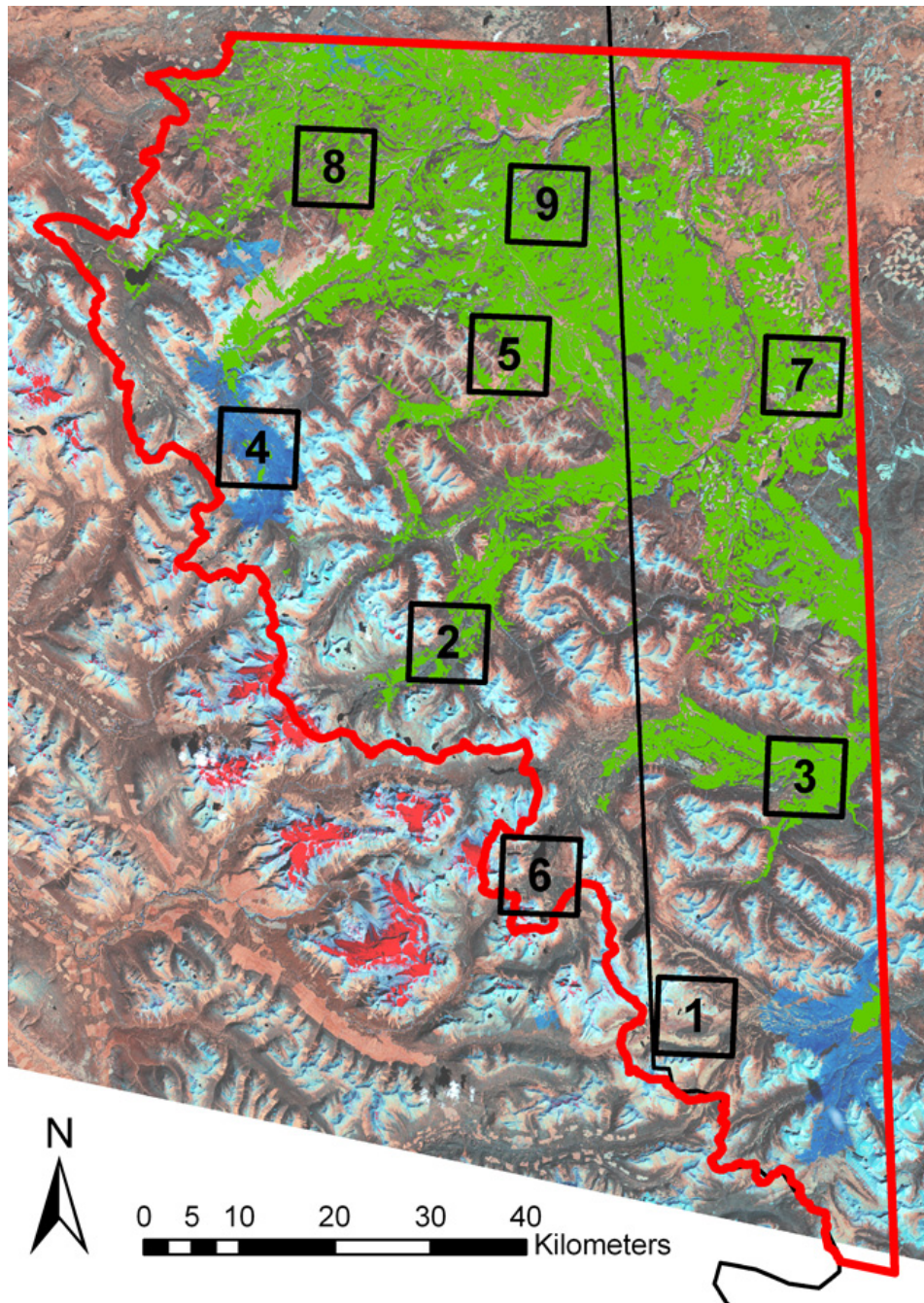
2

1 **Figure 2**



2

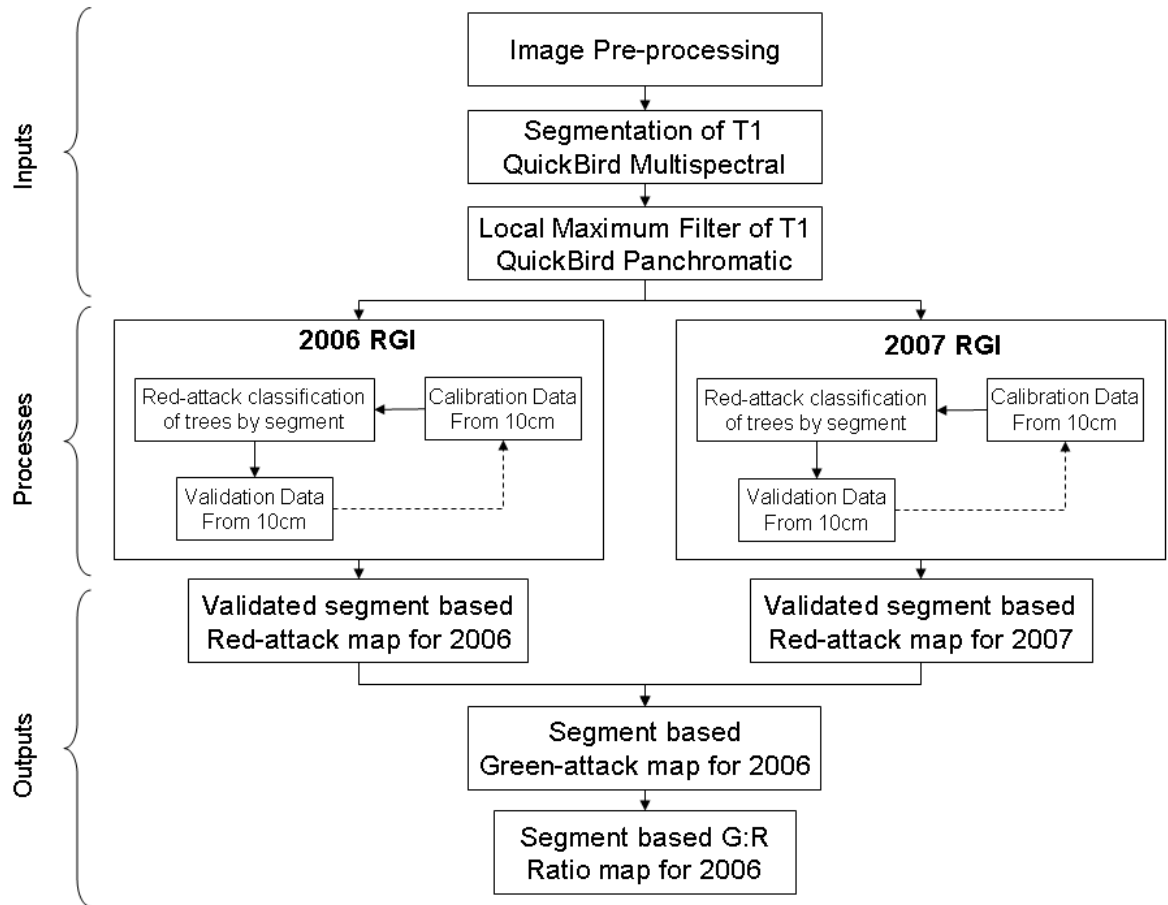
1 **Figure 3**



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1 **Figure 4**

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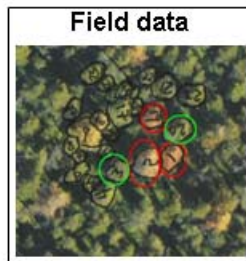


3

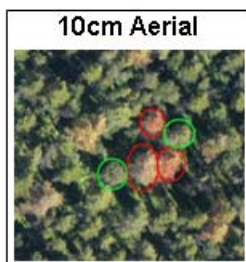
1 **Figure 5**

Data Levels

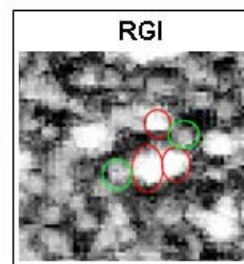
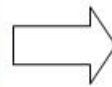
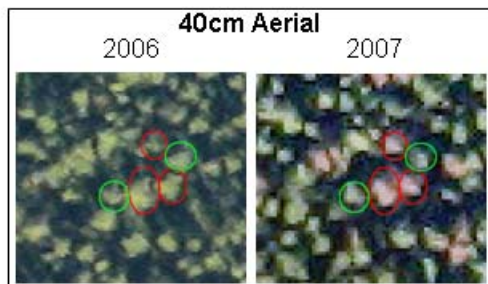
Outputs



Validation of red attack status trees on 10cm imagery.

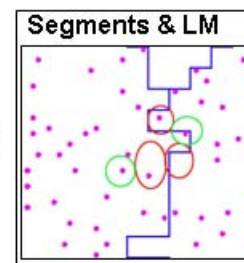
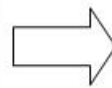
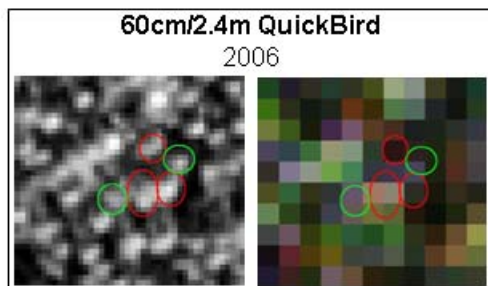


Calibration and validation of local maxima tree counts from QuickBird. Validation of red attack status trees on 40cm aerial imagery, and determination of RGI threshold for red attack tree identification.



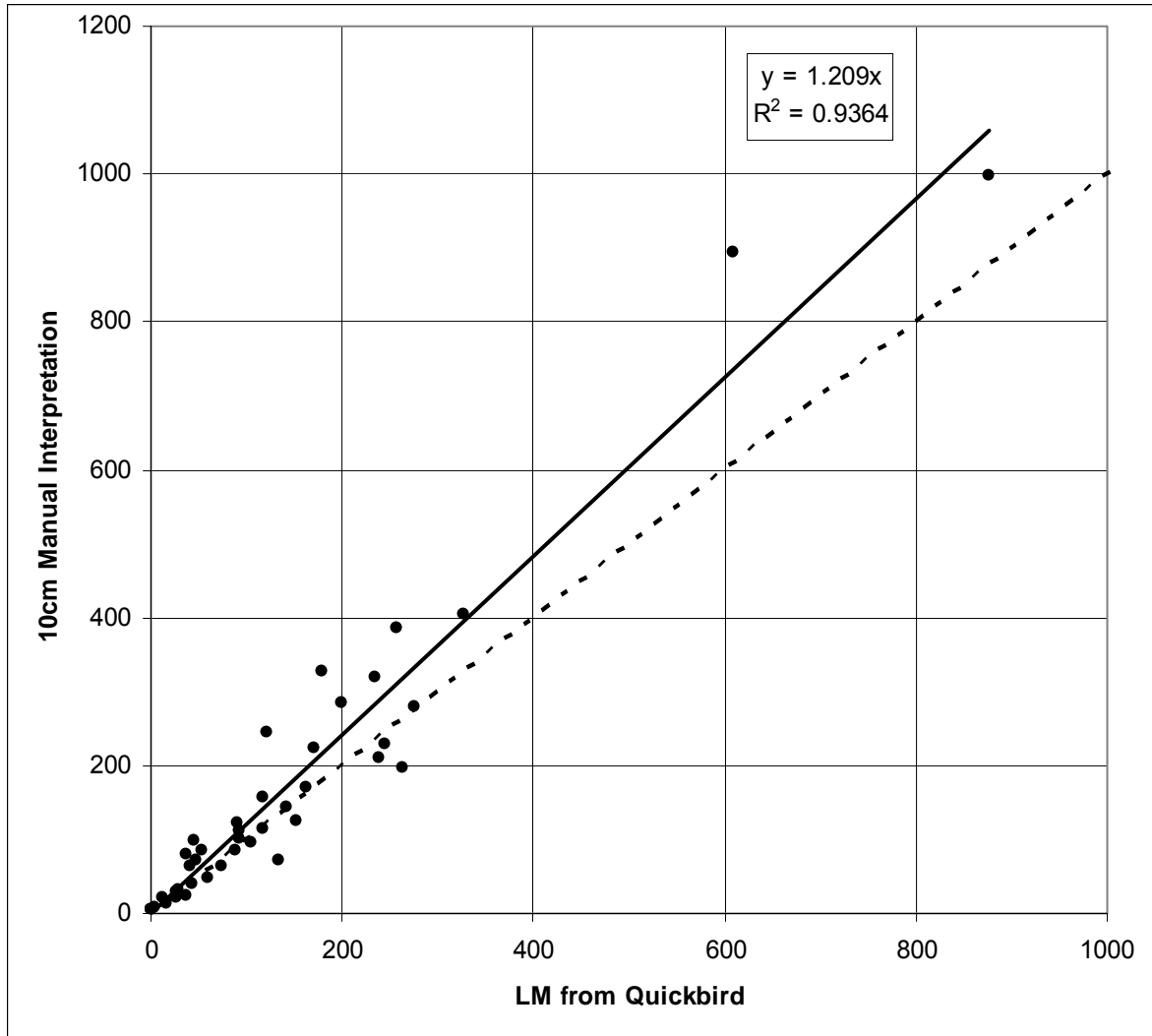
Sample Site coverage for identification of red attack using the RGI.

Segmentation of 2.4m multispectral imagery. Local maxima tree counts from 60cm panchromatic imagery



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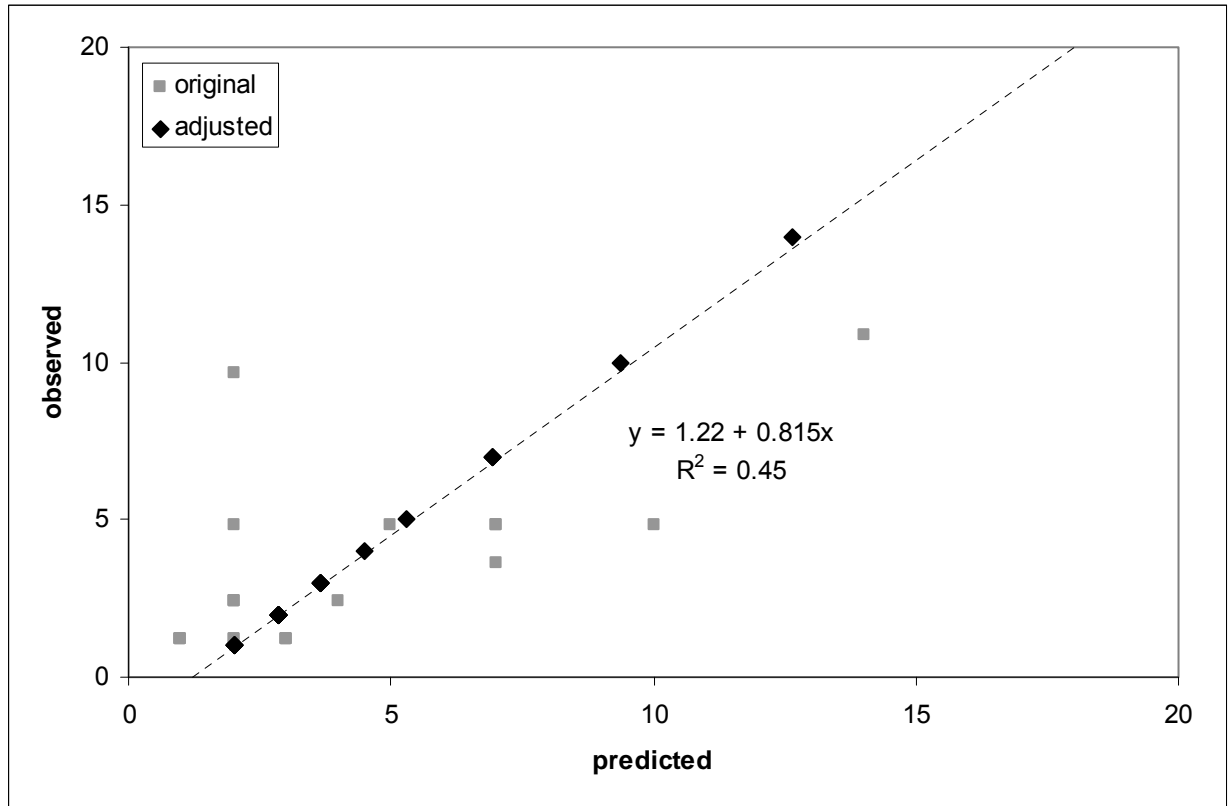
1 **Figure 6**



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1 **Figure 7**

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