Detecting mountain pine beetle red attack damage with EO-1 Hyperion moisture indices

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Hyperion detection of insect attack with moisture indices
Abstract

The mountain pine beetle (Dendroctonus ponderosae) is the most destructive insect of mature pine forests in western North America. Time series of wetness transformations generated from Landsat imagery have been used to detect mountain pine beetle red attack damage over large areas. With the recent availability of high spatial (QuickBird) and high spectral (Hyperion) resolution satellite sensor imagery, the relationship between spectral moisture indices and levels of red attack damage may be investigated. Six moisture indices were generated from Hyperion data and were compared to the proportion of the Hyperion pixel having red attack damage. Results indicate the Hyperion moisture indices incorporating both the SWIR and NIR regions of the electromagnetic spectrum concurrently, such as the Moisture Stress Index, were significantly correlated to levels of damage ($r^2=0.51; p=0.0001$). The results corroborate the hypothesis that changes in foliage moisture resulting from mountain pine beetle attack are driving the broad-scale temporal variation in Landsat derived wetness indices. Furthermore, the results suggest that Hyperion data may be used to map low levels of mountain pine beetle red attack damage over large areas that are not consistently captured with Landsat data.

Keywords: mountain pine beetle, red attack, detection, Hyperion, QuickBird

1. Introduction

The total area impacted by mountain pine beetle (Dendroctonus ponderosae) in the province of British Columbia, Canada, increased from 164,000 ha in 1999 to 8.5 million ha in 2005 (British Columbia Ministry of Forests and Range 2005). Adult beetles typically attack the primary host, lodgepole pine (Pinus contorta), in August and lay eggs, which complete their development cycle into mature adults approximately one year later (Amman and Cole 1983). A synthesis of our present knowledge of mountain pine beetle biology is provided in Safranyik and Carroll (2006).

Immediately following an attack by mountain pine beetle, the foliage of trees remains visibly unchanged; however, a drop in sapwood moisture has been measured as a consequence of the attack (Reid 1961, Yamaoka et al. 1990). Once a tree is killed by mountain pine beetle it will initially retain its green foliage (typically called the green attack stage). Generally, the foliage fades from green to yellow to red over the spring and summer following attack (Amman 1982, Henigman et al. 1999), gradually desiccates, and pigment molecules breakdown (Hill et al. 1967). Twelve-months after being attacked, over 90% of the killed trees will have red needles (red attack). Three years after being attacked, most trees will have lost all needles (gray attack) (British Columbia Ministry of Forests 1995, Wulder et al. 2006a). The variability in the nature and rate of the change in foliage colour often confounds detection efforts.

Detection of red attack damage at the landscape level is generally accomplished using aerial overview surveys (Wulder et al. 2006a). More detailed surveys using helicopters and ground crews are then subsequently undertaken (Wulder et al. 2006b). Aerial photography and high spatial resolution satellite sensor imagery have been used to accurately detect and map red attack damage at the level of individual forest stands and trees (Roberts et al. 2004, White et al. 2005, Coops et al. 2006). White et al. (2005) used
IKONOS imagery to detect red attack damage with accuracies of 70.1% for areas of low infestation (stands with less than 5% of trees damaged) and 92.5% for areas of moderate infestation (stands with between 5% and 20% of trees damaged). Roberts et al. (2004) used scanned airborne photography to detect mountain pine beetle red attack damage with accuracies ranging between 80 and 90%. Coops et al. (2006) used a ratio of red to green reflectance, generated from QuickBird multispectral data, to identify red attack tree crowns. The relationship between the number of red attack pixels and observed red attack crowns was assessed using independent validation data and was found to be significant ($r^2 = 0.48$, $p < 0.001$, standard error = 2.8 crowns).

Over large areas, Landsat Thematic Mapper (TM) and Enhanced Thematic Mapper (ETM+) have been used to detect and map red attack damage at the landscape scale with 81% accuracy in areas where the damage occurs in large, contiguous patches (30-50 red attack trees) (Skakun et al. 2003). Mountain pine beetle red attack damage was detected using the difference between the Kauth and Thomas Tasseled Cap (TCT) wetness component (Kauth and Thomas 1976; Crist and Cicone 1984) calculated for two image dates, referred to as the Enhanced Wetness Difference Index (EWDI) (Skakun et al. 2003). Collins and Woodcock (1996) were the first to characterize forest mortality using the difference between wetness components generated for two dates of TM imagery. The differences in the wetness component were ideally suited to capture change in the SWIR portions of the spectrum, where the change associated with conifer mortality was likely to manifest as an increase in reflectance (due to a decrease in water absorption).

The success of the EWDI as an indicator of red attack damage is related to its ability to discriminate changes in SWIR reflectance, which can be associated with changes in foliage moisture. The availability of hyperspectral remote sensing imagery, with increased spectral resolution in terms of the number and width of the spectral bands in the visible, near-infrared (NIR, 0.7 –1.3 μm), and shortwave infrared (SWIR, 1.300–2.500 μm) regions of the electromagnetic spectrum, facilitates an investigation of the underlying assumptions associated with the EWDI. The results of this investigation could then be used to assess the continued use of the EWDI as a reliable method for detecting and mapping mountain pine beetle red attack damage at the landscape level. In this study, we evaluate the potential of Hyperion, an imaging spectrometer on the Earth Observing 1 (EO-1) satellite platform, to detect mountain pine beetle red attack damage using moisture indices. The performance of Hyperion data is evaluated by direct comparison of Hyperion-derived foliage moisture indices to estimates of red attack damage generated from QuickBird multispectral imagery.

2. Study Area

The study site is located near Merritt, British Columbia, Canada, centered at 49.84° N and 120.75° W. From 2002 to 2005, regular field surveys were conducted in three forest stands in the study area to monitor mountain pine beetle population dynamics. The amount of red attack damage increased markedly between 2003 and 2004; in stand B (Figure 1), there were 6 red attack trees/ha in 2003, increasing to 24 red attack trees/ha in 2004.
3. Data

3.1 QuickBird Imagery

High spatial resolution QuickBird imagery was acquired over the study area on July 20, 2005. The imagery was geocorrected to base planimetric data using a 1st order polynomial cubic convolution (RMS 0.4 m for the panchromatic and RMS 0.9 m for the multispectral). The imagery was acquired with a close to nadir view angle (11.4°) and a high sun elevation of 58.3°. QuickBird imagery contains four multi-spectral bands at 2.44 m spatial resolution: 0.45 - 0.52µm (blue); 0.52 - 0.60µm (green); 0.63 - 0.69µm (red); 0.76 - 0.90µm (near infra-red), and a panchromatic band (0.45- 0.90µm) with a 0.68 m spatial resolution (Birk et al., 2003).

3.2 Hyperion Data

EO-1 was part of NASA's New Millennium Program, implemented to validate new technologies for remote sensing (Ungar et al. 2003) and was launched in November 2000, with an orbit following that of the Landsat-7 satellite. The EO-1 payload carried the Hyperion hyperspectral sensor, consisting of two push-broom imaging spectrometers, designed to cover the visible near-infrared (VNIR) and SWIR regions of the spectrum (Pearlman et al. 2003). Hyperion data has a 30 m spatial resolution and 10 nm spectral resolution ranging from 0.43 to 2.4 µm. A single date of Hyperion data was acquired from the USGS Center for Earth Resource Observation and Science (EROS) data centre. The imagery was collected on August 19, 2005 at level 1R (radiometrically corrected), which includes spectral calibration, smearing and echo correction, use of a bad pixel mask, and alignment of the VNIR and SWIR channels. Common to all Hyperion imagery is evidence of streaks which were corrected by statistical balancing using the means and variances of the columns of the data image (Coops et al. 2003, Datt et al. 2003). The Fast Line-of-sight Atmospheric Analysis of Spectral Hypercubes (FLAASH) (Matthew et al. 2000) algorithm was used to correct the imagery for atmospheric effects. The image was then rectified to the UTM coordinate system to within 0.25 pixel (7 m) accuracy using ground control points. Of the 198 channels, some overlap exists between the two radiometers and a number of channels are not calibrated resulting in 168 usable spectral channels.

4. Methods

4.1 QuickBird data processing

To reduce variability in spectral response, a simple forest/non-forest mask was generated from the four multi-spectral QuickBird bands using a supervised minimum distance classifier. The number of tree crowns with red attack damage was estimated using the ratio of red to green reflectance (Red-Green Index or RGI), which has been demonstrated as an effective approach for estimating the density of red attack crowns on the landscape. The RGI was computed and threshold values based on Coops et al. (2006) were used to discriminate between red attack and non attack tree crowns. This provided a complete census of red attack damage, consistently identified and fully georegistered to the Hyperion data.
4.2 Detection of foliage moisture
Several narrow-band indices have been developed to assess vegetation water content and these indices often ratio two wavelengths, with a band that is insensitive to water content as the numerator, and the water absorption feature either within the NIR or SWIR as the denominator. In this study, six moisture indices were calculated from the Hyperion data using the hyperspectral band closest to the centre of the liquid water absorption feature and a reference band as close as possible to the original band selection (Table 1). Some of the indices were developed specifically using Hyperion data (Roberts et al. 2003), while other indices were developed using hand-held spectrometers (Peñuelas et al. 1993, 1997), airborne hyperspectral data (AVIRIS) (Gao, 1996), or Landsat TM data (Hunt and Rock 1989; Hardisky et al. 1983). For each 30 by 30 m Hyperion pixel, the QuickBird forest/non-forest mask was used to estimate the proportion of forest vegetation within each pixel. For Hyperion pixels which had more than 95% forest, the proportion of the pixel classified as having red attack from an analysis of QuickBird RGI, was then compared to the spectral response in each of the moisture indices.

5. Results
Figure 2 shows the mean surface reflectances retrieved from Hyperion pixels that had varying degrees of red attack damage, as estimated from the QuickBird imagery. The general shape of the retrievals for increasing levels of infestation (no red attack damage, 5, 10, 15, 20, and 25% of the pixel with red attack damage) are similar. The Hyperion pixels with either no red attack damage (0%) or very low levels of red attack damage (0-5%) have more absorption in the chlorophyll absorbance region (680 nm), greater scattering in the NIR, and greater absorbance in the SWIR regions (Figure 2 insert). Alternatively, in the Hyperion pixels with a greater proportion of red attack damage, reflectance is greater in the visible and SWIR regions of the spectrum due to the lower availability of water and pigments in the red attack damaged tree crowns for absorption. The index with the strongest relationship to the proportion of red attack damage was the MSI ($r^2 = 0.51; p < 0.001$) (Figure 3), followed by the NDII ($r^2 = 0.40; p < 0.001$) (Figure 3). The greatest variability in both MSI and NDII values occurred in stands with no or minimal amounts of red attack damage and this may be attributable to the natural variability that is typical of lodgepole pine stands (Skakun et al. 2003)

6. Discussion and Summary
Measures of canopy reflectance collected by hyperspectral systems in the NIR and SWIR regions of the electromagnetic spectrum have been used to estimate canopy moisture (Carter 1991, Danson et al. 1992, Roberts et al. 2003), as both of these spectral regions exhibit pronounced water absorption features. All of the examined Hyperion moisture indices dependent on the 980 nm liquid water band (WBI, WI) had low correlations to the proportion of red attack damage in the Hyperion pixel, resulting from the low signal in this wavelength region (Ungar et al. 2003). Of the remaining indices considered, those with the largest correlation to the proportion of red attack damage in the Hyperion pixel were those indices which utilized the SWIR and NIR regions of the spectrum concurrently; the MSI and NDII both used 819 nm as the non-sensitive wavelength and either 1400 or 1650 nm as the water absorption wavelength. The variability in index
values for stands with no or minimal levels of red attack damage suggest that there is considerable natural variability in these stands, supporting the use of forest structural masks to constrain this variability. In contrast to the WBI and the WI, which were developed with hand-held spectrometers, the MSI was originally developed as a broadband ratio (Landsat TM) that utilizes a combination of the moisture-affected SWIR bands and the theoretically unaffected NIR bands. The TCT Wetness index is a transformation of all Landsat TM or ETM+ spectral bands that is heavily weighted in the SWIR bands, but which also incorporates information from the visible and NIR (Huang et al. 2002). These results support the continued use of the TCT wetness index approach to detect mountain pine beetle red attack damage over large areas.

With respect to the strength of the Hyperion relationships, the results are encouraging in terms of the capacity of the Hyperion narrow-band widths to detect moisture stress. At the study site, the majority of Hyperion pixels had less than 20% of their total area (900 m²) with red attack damage, which, depending on the size of the tree crowns, equates to approximately 15 or fewer damaged tree crowns. In areas where the Landsat EWDI has been applied successfully, the number of trees with red attack damage was often much larger – being in the order of 30 to 50 trees in a 900 m² area (Skakun et al. 2003). This suggests that space-borne hyperspectral imagery may have the capacity to detect lower densities of red attack damage at the landscape scale, which may allow for the earlier identification of small infestation centers, thereby aiding mitigation and control efforts. The capacity to detect low levels of mountain pine beetle red attack damage over large areas is a gap in the current data hierarchy used to monitor mountain pine beetle (Wulder et al., 2006c). As the first spaceborne hyperspectral sensor, Hyperion was designed as a research instrument; however, plans for the launch of spaceborne hyperspectral instruments (Shippert 2004) may present opportunities for detecting low levels of mountain pine beetle red attack damage over large areas.

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